APT1000 Modbus Register Map Firmware Version 7 & 8

lssue: B

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General Note: Parameters with variable numeric values are entered and stored as integer values. The actual value that this integer represents will depend upon the number of decimal places it is scaled to. Register 28 is set during manufacture and defines the number of decimal places set. If set to 1 the Integer value is divided by 10, if set to 2 by 100 and if set to 3 by 1000. For example an integer value of 123456 with register 28 set to 2 would mean an actual value of 1234.56 Refer to the Functionality Column for a description of the meaining of each register.

Factory / User. Factory registers are read only, either as results of the calculation chain, or a fixed factory setting which is for information only. User registers may be edited.

	•	-		•		-			-		Comments
Parameter Description	Register Type	Register Address	Coils/Registers	Default Value	Max Value	Min Value	Functionality of parameter	Short Description	Factory / User Parameter	User Access	
Modbus Slave Address	Word	0	APT1000 Modbus address	1	247	1	Unique modbus address of this APT1000. To change refer to Register 1 description	Unique Modbus ident of the APT1000	User	Read / Write Access	
Enable Modbus Address edit	Bit	1 - Bit 1	Modbus address change enable bit	0	1	0	 This value is set to 0 unless Modbus ident is required to be changed Steps to set the new Modbus slave Address 1) Set this bit to value = 1 and write to APT1000 2) Modify the Modbus slave address (Register 0)with the required Modbus address and write to APT1000 3) Set this bit to value = 0 and write to APT1000 After this final step the device will now only respond to commands addressed to the ident set in Register 0. 	Bit setting to allow change to Modbus ident	User	Read / Write Access	*
Temperature Compensation Enable	Bit	1 - Bit 2	Temperature Compensation Enable Bit	1	1	0	The value of the bit enables or disables temperature compensation. If the bit is set to 1 temperature compensation for presure values is enabled, else if set to 0 the temperature compensation is disabled.	Enble or disable temperature compensation	User	Read / Write Access	
Secondary Measured Value (temperature)	Word	2	Secondary measured value	-	-	-	Temperature in 0.1 °C resolution. Held as an integer value e.g. 25.1 °C is represented as 251.	Measured temeperature value	Factory	Read Only	
Actual Measured Value (Pressure)	Word	4	Actual pressure on sensor hi	The pressure -2,147,483	The pressure values can range from -2,147,483,648 to 2,147,483,647.		Actual pressure in mm H2O currently being measured by the APT1000. This value is held as an integer, but it's actual meaning is defined according to the decimal place	Actual pressure on APT1000 in mm H20	Factory	Read Only	
	vvora	5	Actual pressure on sensor lo				setting in register 28				
	Word	6	Specific gravity	1000	3000	500	Value of the Specific Gravity of the fluid being measured. Value is entered as actual SG x 1000. e.g. for an SG of 1.025 enter 1025	Specific Gravity Value	User	Read / Write Access	
	Word	7	Liquid level above sensor hi				Actual liquid level in mm H2O above sensor location currently being measured by the sensor. Calculated as				
	Word	8	Liquid level above sensor lo	-	-	-	Actual MV (registers 4 & 5) corrected for Specific Gravity (register 6). Value given is an integer, but it's actual meaning is defined according to the decimal place setting in register 28	Liquid level above sensor	Factory	Read Only	
	Word	9	Sensor position offset hi				Zero position offset. i.e. the dimension the sensor is mounted above or below the tank bottom. If the sensor is located below the tank bottom value is optoard as a		User		
	Word	10	Sensor position offset lo	0	100000	-100000	negative number. Enter in millimetres as an integer value. This register is not affected by setting of register 28.	Sensor offset in mm		Access	

Parameters used for Level Calculation	Word	11	Total tank height hi (Firmware version 8.XX and up only)	40000	50000 (IR7.XX)		Enter total tank height in millimetres as an integer value. Total height is defined as from tank base (empty point)	Table d bailtin and	User	Read / Write Access	Note Firmware
	Word	12	Total tank height lo (Firmware version 8.XX and up only). For Firmware version 7.XX only this register is used to define tank height	. 10000	400000 (IR8.XX)	1	to tank top (100% full point). This register is not affected by setting of register 28.	i otal tank height in mm	User	Read / Write Access	only Register 12
	Word	13	Percentage tank level hi				Display of current tank percent level. Value derived				
	Word	14	Percentage tank level lo	-	-	0	based comparing actual level in tank (registers 23 & 24) with total tank depth (register 12). Values are given to 2 decimal places presented as an integer, e.g. a value of 5 = 0.05%.	% tank level	User	Read Only	
	Word	15	Tank capacity hi	100000	16777215	0	Enter total tank volume at the same 100% full point used for tank height (register 12). Enter as an integer value in units of measure to be displayed in, with consideration	Total Tank Volume in required Engineering units	lleer	Read / Write	
	Word	16	Tank capacity lo	100000	10///213	Ŭ	of the number of decimal points set in register 17. For example tank volume 95.682 cubic metres then enter value of 95682 and register 17 would have a value of 3.		User	Access	
Volume Calculation	Word	17	Decimal points - Volume	1	3	0	This register defines the number of decimal points that are to be applied to the integer value held in registers 15 & 16 - Tank Capacity, and registers 18 & 19 - Actual Volume.	Number of decimal points to be applied	User	Read / Write Access	Only implemented in Version 6.7 firmware and above
	Word	18	Actual volume hi				Display of actual content in the tank in the units of measure in use. Calculated by multiplying tank capacily				
	Word	19	Actual volume lo	-	-	0	(registers 15 & 16) by current percentage volume (registers 20 & 21). The value is provided as an integer and is scaled according to the setting of register 17	Current Tank Volume in required Engineering units	Factory	Read Only	
	Word	20	Percentage tank volume hi				Display of current tank percent full. Calculated by taking the value for tank percent full (registers 13 & 14) and comparing this to the corresponding value is the tank				
	Word	21	Percentage tank volume lo	-	-	0	look up table (registers 144 to 243). Value is given to 2 decimal places presented as an integer, e.g. a value of 5 = 0.05%.	% full in volume terms	Factory	Read Only	
RS 485 Delay	Word	22	RS 485 delay time	20	5000	0	This parameter is used to introduce a delay time before the APT1000 responds to a data request from a Master. It may be required for example where Master devices require time to switch from Tx to Rx. The value is entered in milliseconds up to 5000 (5 seconds). The setting is retained if the unit is power cycled. The default value is 20ms.	APT1000 response delay time	User	Read / Write Access	
	Word	23	Actual Level hi				Actual level of liquid in the tank in mm H2O calculated by adding the sensor offset (registers 9 & 10) to the				
Level Calculation (Con't)	Word	24	Actual level lo	-	0	700000	ilquid level above sensor (registers 7 & 8). Value is held as an integer, but actual meaning is defined according to the decimal place setting in register 28	% tull in level terms	Factory	Read Only	
Internal Temperature Calibration	Word	25	Volt equivalent for Ambient temperature set during calibration	821	-	0	Internal factory setting for internal temperature sensor calibration	Internal parameter only	Factory	Read Only	

	Word	26	AD5421 Offset value	0x89D9	OxFFFF	0	Internal factory calibration settings for 4 - 20mA AD		Factory	Read Only	
AD5421 Calibration	Word	27	AD5421 Gain value	0xC4ED	OxFFFF	0	conversion	internai parameter oniy	Factory	Read Only	*
Number of decimal points for level values	Word	28	Decimal points - Level	1	3	0	This factory set register defines the number of decimal places that the APT1000 is factory calibrated to. It is set at a value of 1 which means the calbiration is to a resolution of 0.1mm H2O. It is also used as a scaling factor for integer values which are entered into or held in the following registers. Pressure Calibration - registers 442 to 451, Actual Pressure - registers 4 & 5, Actual Level - registers 23 & 24, mA Zero value - registers 104 & 105, mA Span value - registers 106 & 107 , Min Pressure - registers 35 & 36, Max Pressure- registers 33 & 34, Liquid Level - registers 7 & 8, and Pressure Offset - registers 40 & 41. For all of these listed registers the appropriate decimal place should be inferred. For example a value of 1 in register 28 would mean that an integer value of 1000 had the actual meaning of 100.0	Internal parameter only	Factory	ictory Read Only	
Internal Temperature Calibration (Con't)	Word	29	Ambient temperature	250	-	0	Internal factory calibration setting for internal temperature sensor	Internal parameter only	Factory	Read Only	
Status Register	Word	30	Status Register	0	31	0	This status of bits in this register identifies if errors have been detected. Some, depending whether they are enabled (in register 31) can also force the mA output to a fixed value. Bit 0 is set when a negative level is detected. This parameter is for information only and should NOT be used to force the analogue outpt to a fault value. Bit 1 is set if the sensor reads a pressure input higher than the accepted maximum of 70000mm. If enabled in register 31 the mA output is driven to the 21mA fault condition. Bit 2 is not used, it is reserved for future use. Bit 3 is set to indicate that the percentage level calculated has exceeded 100%. If it is set and the value exceeds the tolerance percentage value specified in register 42 the mA output will drive to 21mA if this is enabled in register 31. Bit 4 is set if the percentage level calculated has exceeded 100%. It will not trigger any fault current. Bit 5 is set when the percentage level calculated is less than 0%. If set and the value is lower than the tolerance percentage value specified in register 31.	Error status flags	Factory	Read Only	

	Word	31	Status register mask	42	127	0	The settings in this register determine which of the error status conditions identified in register 30 trigger the mA fault signal. Note that the mA fault signal is only active for as long as the relevant error is present. If the error bit clears the mA signal will revert to normal operation. Note that the bits identified in register 30 are read from the most significant bit, i.e. this register would have a value of 010000000000000 where Bit 1 is required to drive the mA signal to 21mA. The default value is 010101000000000	Enable mA fault current conditions	User	Read / Write Access
Manufacturing Mode Access	Word	32	Manufacturing mode passkey	-	-	-	For factory use only	Internal parameter only	Factory	No Access
	Word	33	Maximum pressure hi	The pressure	The pressure values can range from		Records the maximum pressure measured by the sensor during its operational lifetime. Value is stored as an	Stored maximum pressure history	Factory	Read Only
	Word	34	Maximum pressure lo	-2,147,483,	648 to 2,147,	483,647.	integer but actual meaning is defined according to the decimal place setting in register 28		Factory	
	Word	35	Minimum pressure hi	The pressure	he pressure values can range from Records the minimum pressure recorded by the sensor during its operational lifetime. Value is stored as an		Records the minimum pressure recorded by the sensor during its operational lifetime. Value is stored as an		Factory	Read Only
Min/Max Recording	Word	36	Minimum pressure lo	-2,147,483,	648 to 2,147,	7,483,647. integer, but actual meaning is defined according to the decimal place setting in register 28		Satored minimum pressure history	Factory	
	Word	37	Maximum temperature	-	R the as		Records in °C the maximum temperature recorded by the sensor during its operational lifetime. Value is stored as an integer with one decimal place impied. e.g. 80 °C would be recorded as 800		Factory	Read Only
	Word	38	Minimum temperature	-	-	-	Records in °C the minimum temperature recorded by the sensor during its lifetime. Value is stored as an integer with one decimal place impied. e.g. 5 °C would be recorded as 50	Stored minimum temperature history		
Percentage range offset	Word	39	Percentage range offset	0	10000	0	This register is only relevant if the value of register 250 is set to 0 or 1 to relate the mA output to either % level or % volume. If used it defines the percentage value for either level or volume for which the APT1000 will output 20 mA. The value entered has the decimal point fixed to 2 places, e.g. enter 5000 for 50.00%.	mA output scaling value - depending on setting of register 250	User	Read / Write Access
	Word	40	Pressure Trim Hi		The pressure values can range from -2,147,483,648 to 2,147,483,647.		This register allows a millimetres offset to be added to the pressure the APT1000 is reading. i.e. the Actual MV (address 4 & 5). All parameters which are calculated using the Actual MV value will then use Actual MV plus the value stored in this register. One example of it's use			
Sensor Offset	Word	41	Pressure Trim Lo	The pressure -2,147,483,			he value stored in this register. One example of it's use vould be to correct a zero offset error on the APT1000. ne value may be positive or negative. Enter the value as an integer. It's actual value will be determined by the number of decimal places set by register 28. For example if register 28 is set as 1 then 12345 will have the meaning 1234.5		om User	Read / Write Access

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Alarm Tolerance	Word	42	Alarm Tolerance Percentage	500	-10000	10000	If the mA output is set in register 31 to go to a fault state where the percentage level calculation returns a value either less than 0% or more than 100%, this will only happen if the percentage value calculated also exceeds the alarm tolerance specified in this register. e.g. if percentage level value is calculated as 103% and tolerance is set to 5% in this register then the status register (30) will indicate a tank level percentage overflow condition and the percentage level register (13 & 14) will be clamped to 100% but no fault current output will be triggered even if status mask register (31) enables it. If however, the percentage level is calculated at 106%, the percentage level register will remain clamped at 100%, status register 30 will have the status bit set and the fault current will be now be triggered - if status mask 31 enables it. The setting of this register applies both to the low state (below 0%) and the high state (above 100%). The value is entered as an integer with 2 decimal places fixed, e.g. 5.00% entered as 500	Alarm tolerance for out of limits paramters (to determine if fault current is enabled)	User	Read / Write Access
Uncompensated Actual MV	Word	47	Uncompensated Actual MV Hi	The pressure	The pressure values can range from		The register shows the actual MV value calculated	Actual MV before Temperature compensation	Factory	Read Only
	Word	48	Actual MV Override Hi	-2,147,483	-2,147,403,040 to 2,147,403,047.		For factory testing only. The values entered into these			
Actual MV Override	Word	50	Actual MV Override Lo	The pressure values can range from ^r -2,147,483,648 to 2,147,483,647.		ange from 483,647.	registers are used to replace the actual MV. The purpose is to enable Factory testing of the Temperature compensation. For normal operation these registers must be set to 0	Simulation of MV for Temp Comp testing	Factory	Read Only
Temperature Override	Word	51	Temperature override	-	t		For Factory testing only. The value entered into this register is used to replace the actual temperature read by the device. The purpose is to enable Factory testing of the Temperature compensation. For normal operation the register must be set to 0	Temperature reading simulation	Factory	Read Only
RS 485 Termination resistor	Bit	53	RS 485 internal termination resistor control	0	1	0	If set to 1 the termination resistor for RS 485 is enabled. If set to 0 the termination resistor is disabled.	Enable / disable RS485 Terminating resistor	User	Read / Write Access
	Word	104	Zero point pressure hi		1	1	The settings in this register are only considered if			
	Word	105	Zero point pressure lo	The pressure	e values can ra	ange from	register 250 is set to 3. They define the actual pressure value (from register 4 & 5) that corresponds to 4mA output. It is entered as an integer but it's actual value is defined according to the decimal place setting in register 28	Pressure value for 4mA output (only if ragister 250 is set to 2)	User	Read / Write Access
4-20mA Output Scaling	Word	106	Span point pressure hi	-2,147,483	,648 to 2,147,	483,647.	The settings in this register are only considered if			
	Word	107	Span point pressure lo				register 250 is set to 3. They define the actual pressure value (from register 4 & 5) that corresponds to 20mA analogue output. It is entered as an integer but it's actual value is defined according to the decimal place setting in register 28	Pressure value for 20mA output (only if ragister 250 is set to 2)	User	Read / Write Access
	Word	143	Profile points used	25	25	0	Number of points to be used from the tank look-up table, a maximum of 25 points can be used. See registers 144 to 243. If the tank is linear such that the percentage leval and percentage volume track each other identcally it is acceptable to use only 2 data points, a pair at 0% and a pair at 100%	Tank Look up table % level point	User	Read / Write Access
	Word	144	%level look-up point 1 hi				Entry of up to 25 LEVEL data points (as defined by	Tank Look up table % level point		
	Word	145	%level look-up point 1 lo				register 143) for the tank look-up. Table Point 1	Tank Look up table % level point		
	Word	146 to 191	1 %level look-up points 2 to 24	-			(registers 144 & 145) being the lowest level. Value is entered as percentage level in an integer value to 2	Tank Look up table % level point		
	woru	192	%ever look-up point 25 m					Tank Look up table % level point		

							decimal places. E.g. 51.26% level would be entered as			Road / Mirita
					10000		5126. The values entered must increase from the previous register. The final value must be 100.00%		User	Access
Tank look-up table	Word	193	%level look-up point 25 lo				entered as 10000. If there are any unused points, then	Tank Look up table % level point		
							the value of register 143 must be reduced to the actual number of points, or unused data points must be			
				Linear Table		#REE!	entered as 100.00%, i.e. 10000			
	Word	194	%volume look-up point 1 hi			miller :	Entry of up to 25 VOLUME data Points for the	Tank Look up table % volume point		
	Word	195	%volume look-up point 1 lo				corresponding % volume at the % level points entered	Tank Look up table % volume point		
	Word	196 to 241	%volume look-up points 2 to 24				between registers 144 to 193. Table point 1 (registers	Tank Look up table % volume point		
	Word	242	%volume look-up point 25 hi				(registers 144 & 145). The values entered must increase	Tank Look up table % volume point		Read / Write
	Word	243	%volume look-up point 25 lo		10000		from the previous register. The final value must be 100.00% entered as 10000. If there are any unused points, then the value of register 143 must be reduced to the actual number of points, or unused data points must be entered as 100.00%, i.e. 10000	Tank Look up table % volume point	User	Access
							Averaging is performed according to the value of this			
							register (n). In operation this means that the APT1000			
User Filter	Word	249	User filter value	1	1200	1	will take the value of "n" samples summate them and divide by n to obtain an averaged value. Minimum value	Filter value (signal averaging)	User	Read / Write
				_		_	is 1 maximum value is 1200. Internal samples are taken			Access
							every 90 m/sec so for example a setting of 20 will give			
							This register defines which parameter the 4-20mA			
							% of tank volume - based on registers 20 & 21			
							1 = % of tank level - based on registers 13 & 14			
							Actual pressure based on register 4 & 5 where 4mA is			
Selection	Word	250	Analogue output source	3	5	0	defined as calibration pressure point 1 - registers 442 &	4-20mA output scaling parameter	User	Access
							443, and 20mA is defined as calibration pressure point 5 registers 450 & 451 4 = analogue output is off -			
							fixed at 3.2mA 5 = Forced output. This allows			
							for testing of the mA output and connected instruments			
							register 263)			
							This register is used to set the value of the mA output			
							when the "forced analogue output mode" is selected in			Deed (Market
Forced Output	Word	263	Forced analogue output percentage	0	10000	0	analogue output source (register 250). Enter as a percentage of 4-20mA output with fixed 2 decimal	Manual setting of mA value for test purposes	User	Access
							places e.g. 50.00% is entered as 5000.			
							I ne register decides the accuracy of the temperature coefficients entered. The part of the temperature			
	Word	299	Resolution	6	6	0	coefficient after the decimal point is made into a n	temperature compensation resolution	Factory	Read Only
							decimal place accurate value, where n is the value			
			Transie and finite the Obstance				stored in the resolution register.			
Temperature compensation	Word	300	part Hi (a01 h)							
coefficient	Word	301	Temperature coefficient 1_0 Integer part Lo (a01 l)							
	Word	302	Temperature coefficient 1_0 Decimal	Values can var 2,	ry from-2,147, 147,483,647	483,648 to	Coefficients used for temperature compensation.	Temperature compensation coefficients	Factory	Read Only
	Word	202	Temperature coefficient 1_0 Decimal							
	Word	303	part Lo (a01 dl)							
	Word	304 to 379 400	4 coefficients per point for 5 points ADC output calibration point 1 hi	_	-	-		Internal parameter only		
	Word	401	ADC output calibration point 1 lo	-	-	-	j t	Internal parameter only		

	Word	402	Point 2	-	-	-		Internal parameter only		
	Word	403	Foint 2	-	-	-		Internal parameter only		
	Word	404	Point 3	-	-	-	Internal Factory set parameters for Five point ADC	Internal parameter only	Factory	Read Only
	Word	405	101110	-	-	-	calibration	Internal parameter only	T detery	inclu only
	Word	406	Point 4	-	-	-	-	Internal parameter only	-	
	Word	407		-	-	-	-	Internal parameter only	-	
	Word	408	Point 5	-	-	-	-	Internal parameter only	-	
	word	409		-	-	-		Internal parameter only		
	Word	442	Pressure calibration point 1 hi	4				Internal parameter only		
Sensor calibration	Word	443	Pressure calibration point 1 lo					Internal parameter only		
	Word	444	Point 2					Internal parameter only		
	Word	445						Internal parameter only		
	Word	446	Def el 2	The pressu	re values can ra	nge from	Internal stored parameters for factory pressure	Internal parameter only	Factor	Devel Only
	Word	447	Point 3	-2,147,483	3,648 to 2,147,4	83,647.	calibration. Values stored as integer with 3 decinal places implied. i.e. 5000000 means 5000.000	Internal parameter only	Factory	Read Only
	Word	448						Internal parameter only		
	Word	449	- Point 4					Internal parameter only		
	Word	450						Internal parameter only		
	Word	451	Point 5					Internal parameter only		
	Word	1000	Serial Number	0	4294967295	0	Unique factory set Customer instrument serial number	Factory set Serial Number	Factory	Read Only
V V	Word	1001	Eirmware version	_		-	Firmware version. Shown as integer with one decimal	Firmware Version	Factory	Read Only
	Word	1005					place implied i.e. 65 means 6.5			
Manufacturer Details	Word	1006	Factory Serial Number	0	4294967295	0	Internal factory serial number	Internal parameter only	Factory	Read Only
	Word	1007		0	4204067205	0	Fosters records DCD Datab		Frietric	Deed Only
	Word	1008	PCB GRN	0	4294967295	0	Factory record: PCB Batch	internal parameter only	Factory	Read Only
	Word	1009	Sensor nominal range	0	4294967295	0	Factory record: Nominal range of element	Internal parameter only	Factory	Read Only
	word	1010					Fastan, record, Sancar tuna			
Sensor Type	Word	1011	Sensor type	1	3	1	1 = Gauge 2 = Absolute 3 = Compound	Internal parameter only	Factory	Read Only
	Word	1012	User unit characters 1 & 2	-	-	-		User configured name for Sensor / Duty		
	Word	1013	User unit characters 3 & 4	-	-	-		User configured name for Sensor / Duty		
	Word	1014	User unit characters 5 & 6	-	-	-		User configured name for Sensor / Duty	-	
	Word	1015	User unit characters 7 & 8	-	-	-		User configured name for Sensor / Duty	-	
Llass Dafin ad Llaita	Word	1016	User unit characters 9 & 10	-	-	-	Free formet entring to a menimum 20 shorestore	User configured name for Sensor / Duty	l le en	Read / Write
User Defined Units	Word	1017	User unit characters 11 & 12	-	-	-	Free format entry up to a maximum 20 characters	User configured name for Sensor / Duty	User	Access
	Word	1018	User unit characters 13 & 14	-	-	-		User configured name for Sensor / Duty		
	Word	1019	User unit characters 15 & 16	-	-	-		User configured name for Sensor / Duty		
	Word	1020	User unit characters 17 & 18	-	-	-		User configured name for Sensor / Duty		
	Word	1021	User unit characters 19 & 20	-	-	-		User configured name for Sensor / Duty		
	Word	1022	Customer tagging 1 & 2	-	-	-		User configured name for Sensor / Duty		
	Word	1023	Customer tagging 3 & 4	-	-	-		User configured name for Sensor / Duty		
	Word	1024	Customer tagging 5 & 6	-	-	-		User configured name for Sensor / Duty		
	Word	1025	Customer tagging 7 & 8	-	-	-		User configured name for Sensor / Duty		
Customer tagging	Word	1026	Customer tagging 9 & 10	-	-	-	Free format entry up to a maximum 20 characters	User configured name for Sensor / Duty	User	Read / Write
	Word	1027	Customer tagging 11 & 12	-	-	-		User configured name for Sensor / Duty		Access
	Word	1028	Customer tagging 13 & 14	-	-	-		User configured name for Sensor / Duty		
	Word	1029	Customer tagging 15 & 16	-	-	-		User configured name for Sensor / Duty		
	Word	1030	Customer tagging 17 & 18	-	-	-		User configured name for Sensor / Duty		
Wo	Word	1031	Customer tagging 19 & 20	-	-	-		User configured name for Sensor / Duty		
Actual Calibrated Range	Word	1032	Sensor Actual Calibrated Range hi	-	-	-	Factory note: Record of Sensor actual calibrated range in	Internal parameter only	Factory	Read Only
. istaal cansiated hunge	Word	1033	Sensor Actual Calibrated Range lo	-	-	-	millimetres H2O.		ractory	neud Only

Dafault Value Table for Level and Volume look up Table									
	%Lvl	%Vol	Actual Value stored in register						
1	0	0	0						
2	5	5	500						
3	10	10	1000						

4	15	15	1500
5	20	20	2000
6	25	25	2500
7	30	30	3000
8	35	35	3500
9	40	40	4000
10	45	45	4500
11	50	50	5000
12	55	55	5500
13	60	60	6000
14	65	65	6500
15	70	70	7000
16	75	75	7500
17	80	80	8000
18	85	85	8500
19	90	90	9000
20	95	95	9500
21	100	100	10000
22	100	100	10000
23	100	100	10000
24	100	100	10000
25	100	100	10000